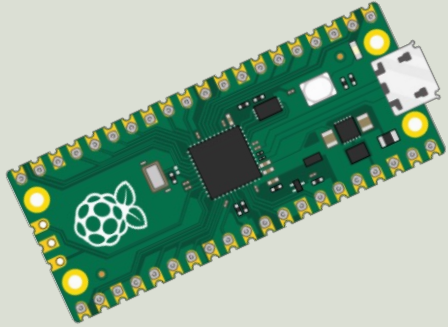


<https://www.halvorsen.blog>



Raspberry Pi Pico

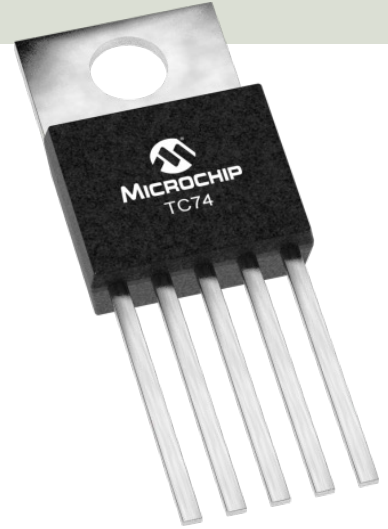
I2C Communication using TC74 Temperature Sensor



Hans-Petter Halvorsen

Contents

- Introduction
- Raspberry Pi Pico
- I2C Communication
- TC74 Temperature Sensor with I2C Interface
 - Python Examples using MicroPython and TC74
 - Datalogging and Data Analysis Examples



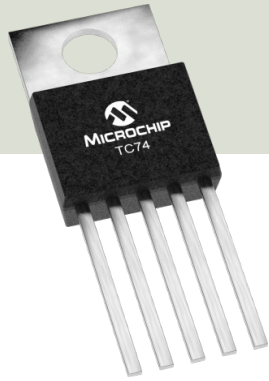


Introduction

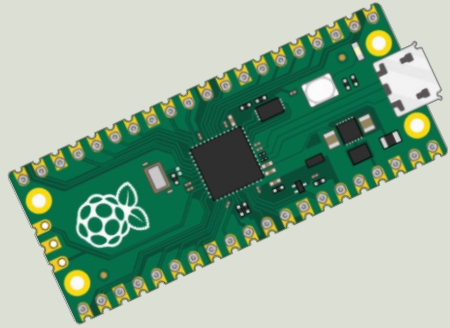
Introduction

- In this Tutorial we will use a Raspberry Pi Pico and I2C Communication
- We will exemplify using a TC74 Temperature Sensor with I2C Interface
- We will use the Thonny Python Editor and MicroPython

What do you need?



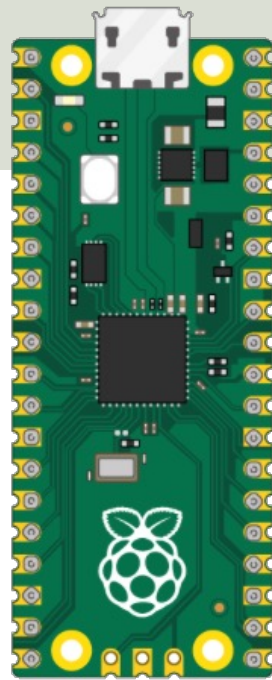
- Raspberry Pi Pico
- A Micro-USB cable
- A PC with Thonny Python Editor (or another Python Editor)
- Breadboard
- Electronics Components like LED, Resistors, Jumper wires, etc.
- **I2C Sensor**, we will use a **TC74** Temperature Sensor with I2C Interface in this Tutorial



Raspberry Pi Pico

Raspberry Pi Pico

- Raspberry Pi Pico is a microcontroller board developed by the Raspberry Pi Foundation
- Raspberry Pi Pico has similar features as Arduino devices
- Raspberry Pi Pico is typically used for Electronics projects, IoT Applications, etc.
- You typically use MicroPython, which is a downscaled version of Python, in order to program it

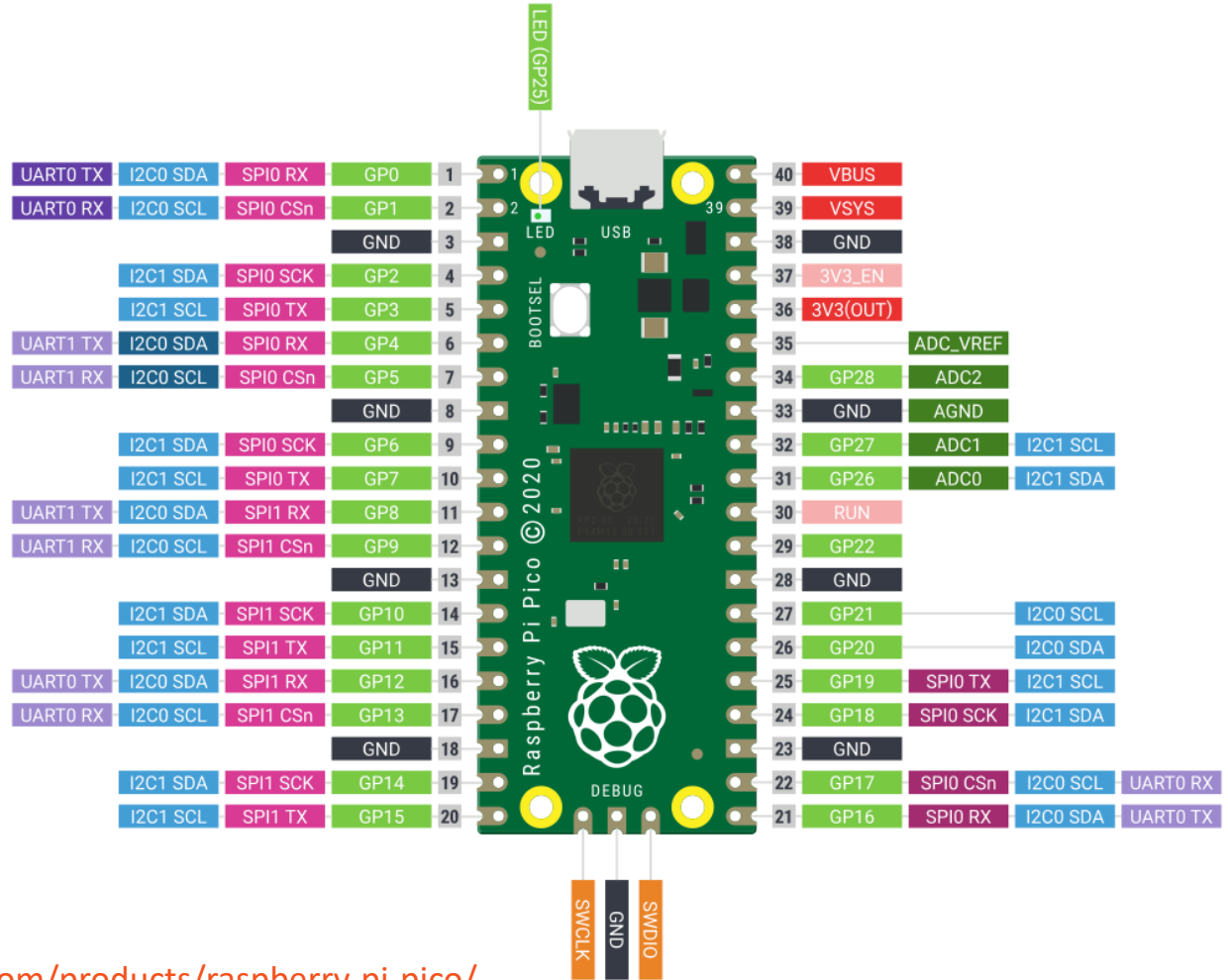


<https://www.raspberrypi.com/products/raspberry-pi-pico/>

<https://projects.raspberrypi.org/en/projects/getting-started-with-the-pico>

Pico Pinout

■	Power
■	Ground
■	UART / UART (default)
■	GPIO, PIO, and PWM
■	ADC
■	SPI / SPI (default)
■	I2C / I2C (default)
■	System Control
■	Debugging



Thonny

```
Thonny - C:\Temp\Raspberry Pi Pico\LED Example.py @ 3:1
File Edit View Run Tools Help

Files
This computer
C:\Temp\Raspberry Pi Pico
LED Example.py
PicoSensor.py
ReadTemp.py

Raspberry Pi Pico
TemperatureSensor.py
thermistor_ex2.py

LED Example.py
1 import machine
2 import time
3
4 pin = 16
5 led = machine.Pin(pin, machine.PIN_CONFIG_LIST[pin])
6
7 while True:
8     led.value(1)
9     time.sleep(2)
10    led.value(0)
11    time.sleep(2)

Shell
MicroPython v1.19.1 on 2022-06-18; Raspberry Pi Pico with RP2040
Type "help()" for more information.
>>> print("Hello World")
Hello World
>>>
```

- Thonny is a simple and user-friendly Python Editor
- Cross-platform: Windows, macOS and Linux
- Built-in support for the Raspberry Pi Pico hardware/MicroPython firmware
- Its free
- Download: <https://thonny.org>

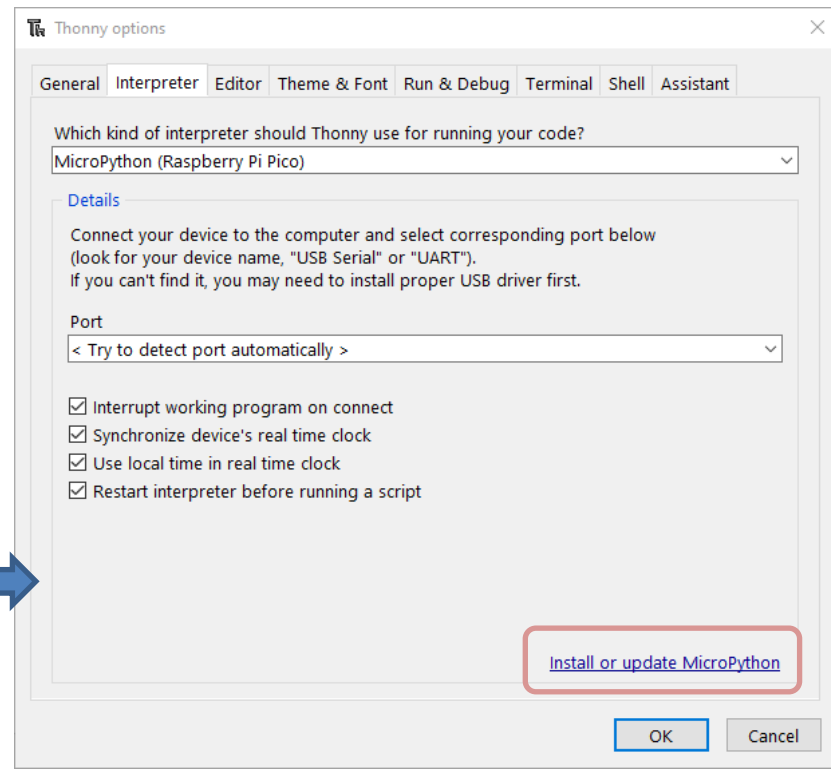
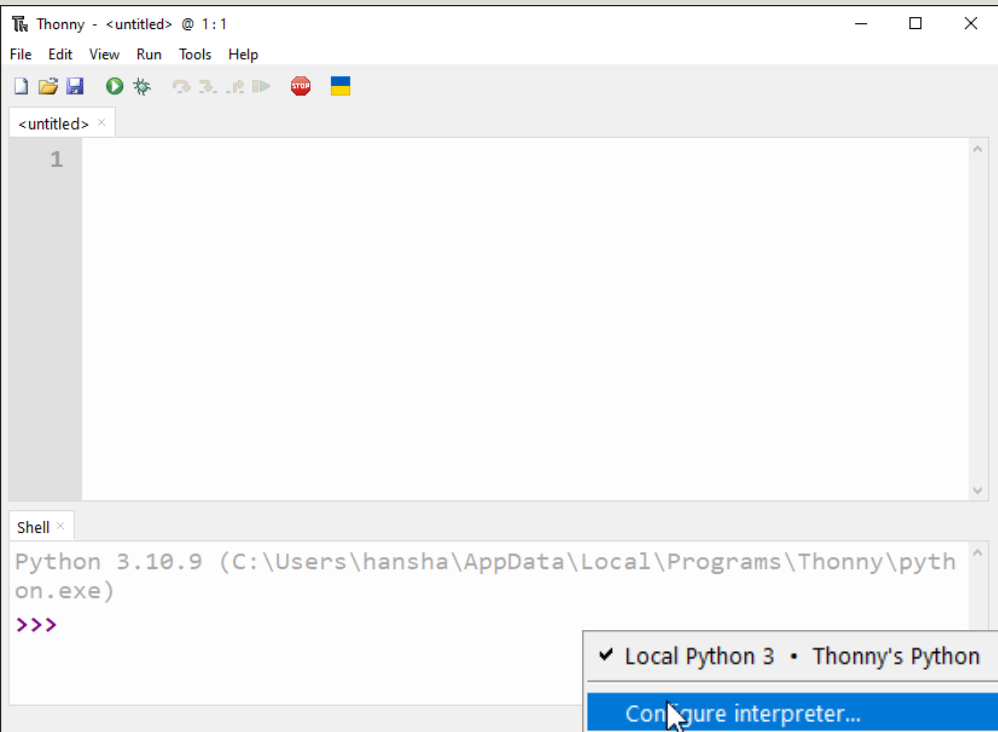
MicroPython

- **MicroPython is a downscaled version of Python**
- It is typically used for Microcontrollers and constrained systems (low memory, etc.)
- Examples of such Microcontrollers that have tailormade MicroPython firmware are Raspberry Pi Pico and Micro:bit
- <https://micropython.org>
- <https://docs.micropython.org/en/latest/>

MicroPython Firmware

- The first time you need to install the MicroPython Firmware on your Raspberry Pi Pico
- You can install the MicroPython Firmware manually or you can use the Thonny Editor

Install MicroPython Firmware using Thonny





I2C Communication

Inter-Integrated Circuit (I²C)

Hans-Petter Halvorsen

[Table of Contents](#)

I2C

- With the I2C protocol you can communicate using just two wires, a clock and data line (+ Power and GND)
- Typically you use I2C to talk to devices like sensors, small displays, PWM or motor drivers, and other devices.
- The Sensor you want to communicate with needs to support the I2C protocol
- There exist thousands of different Sensors, etc. that support the I2C Protocol
- Most Microcontrollers today supports I2C Communication

I2C

- I2C is a multi-drop bus
- 2-Wire Protocol: SCL (Clock) + SDA (Data)
- Multiple devices can be connected to the I2C pins on the Raspberry Pi Pico
- Each device has its own unique I2C address

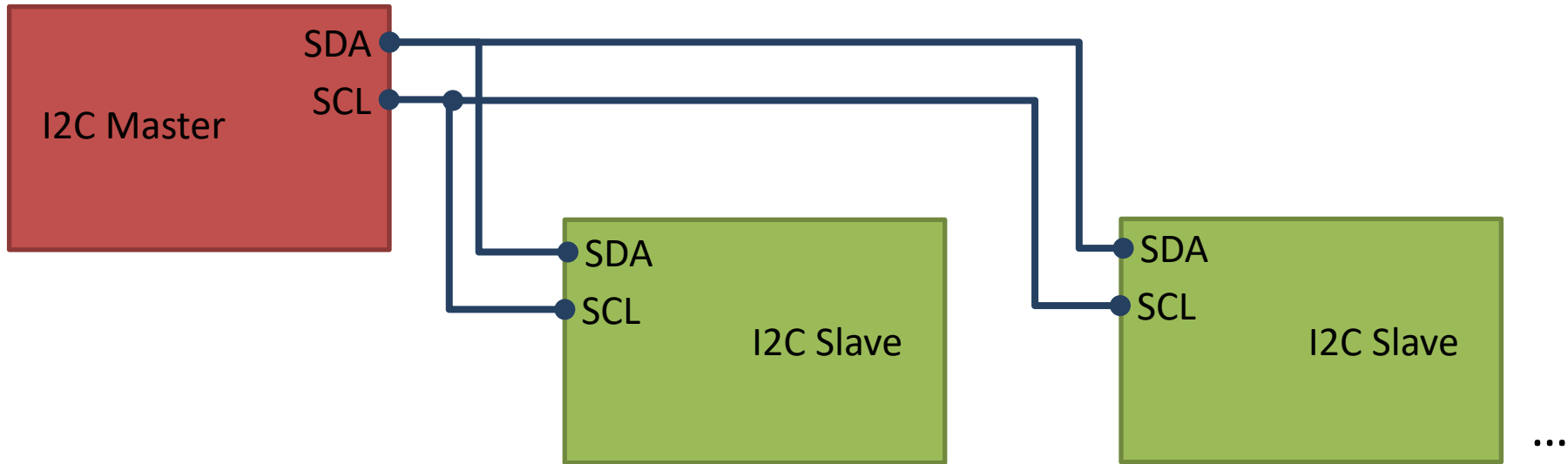
I2C

Multiple devices can be connected to the I2C pins on the Arduino

Master – Device that generates the clock and initiates communication with slaves

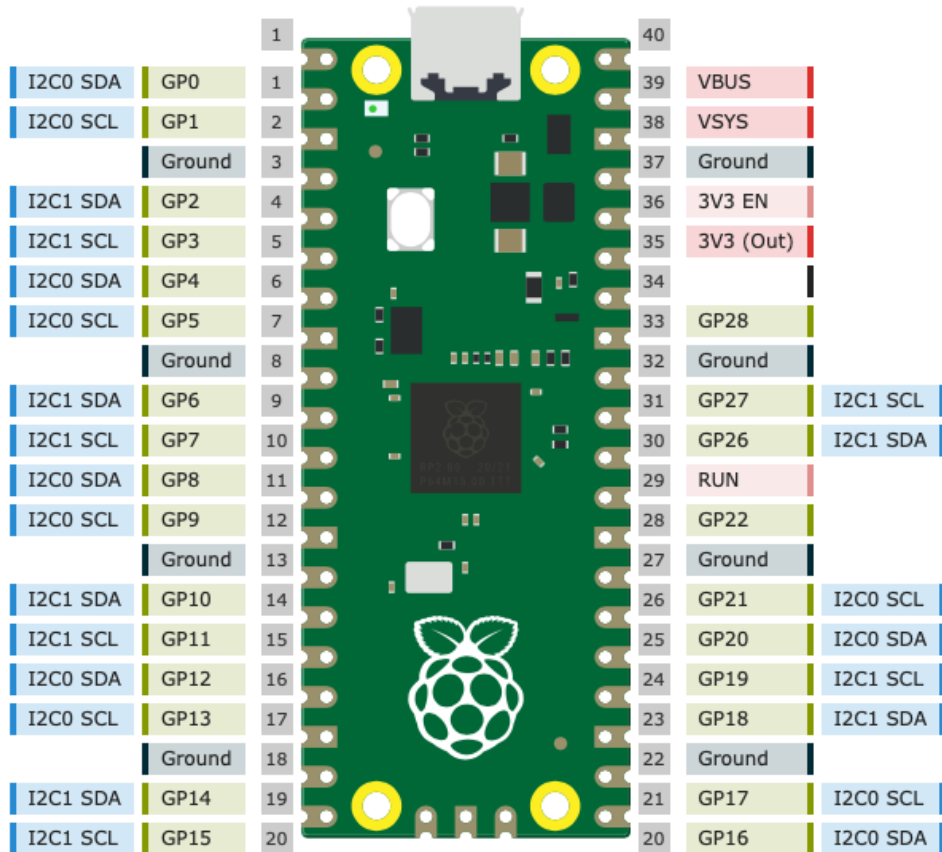
Slave – Device that receives the clock and responds when addressed by the master.

Microcontroller



ADC, DAC, Sensor, etc. with I2C Interface

I2C with Pico



- **Raspberry Pi Pico has 2 I2C Controllers (0 and 1).**
- You can access these I2C controllers through most of the GPIO pins of Raspberry Pi Pico.
- So, you should configure in **software** (your MicroPython program) which GPIO pins you want to use with a specific I2C controller.

I2C with Pico

```
from machine import I2C
```

Initialize I2C Communication: Raspberry Pi Pico has 2 I2C Controllers/Interfaces (0 and 1)

```
i2c = I2C(i2c_interface, scl=sclpin, sda=sdapin, freq=100000)
```

“freq” should be an integer which sets the maximum frequency for SCL

Read Data from the connected I2C device:

```
data = i2c.readfrom(address, n, True)
```

Read n bytes from the peripheral specified by address. If True is set, then a STOP condition is generated at the end of the transfer. The function returns a bytes object with the data.

Many other I2C functions do exist, see documentation :

<https://docs.micropython.org/en/latest/library/machine.I2C.html>

Python – Scan for I2C Devices

```
from machine import Pin, I2C

i2c_interface = 0

sdapin = Pin(16)
sclpin = Pin(17)

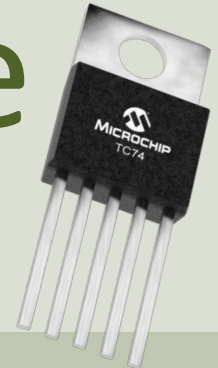
i2c = I2C(i2c_interface, scl=sclpin, sda=sdapin, freq=100000)

i2cdevices = i2c.scan()

print(i2cdevices)
```



TC74 Temperature Sensor with I2C Interface

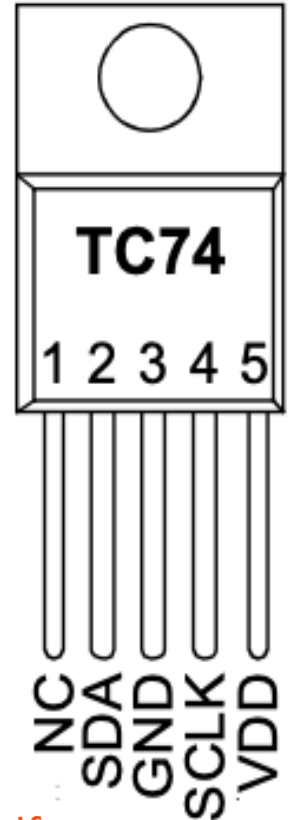
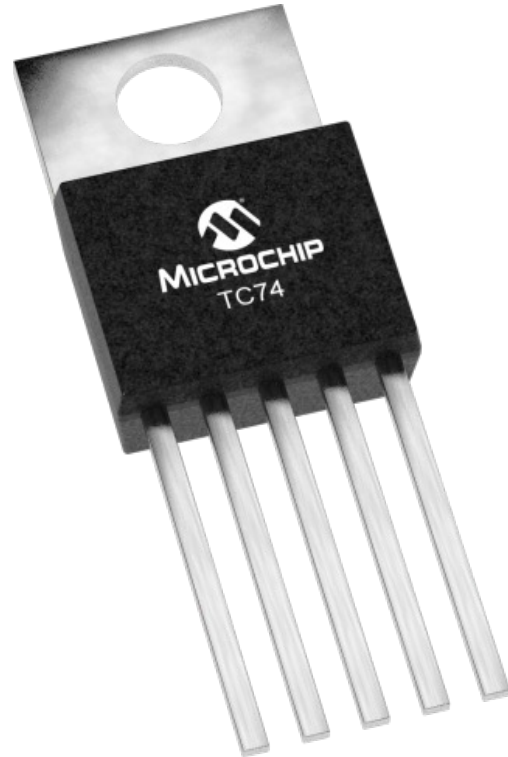


Hans-Petter Halvorsen

[Table of Contents](#)

TC74 Temperature Sensor

Make sure to buy the
breadboard friendly **TO-220**
package version of the sensor

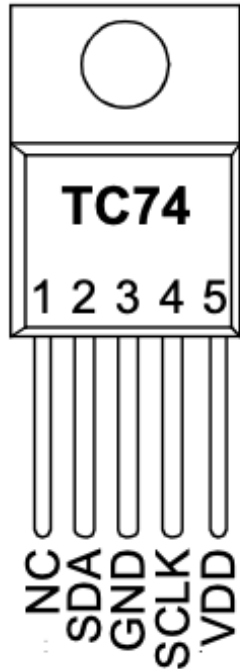
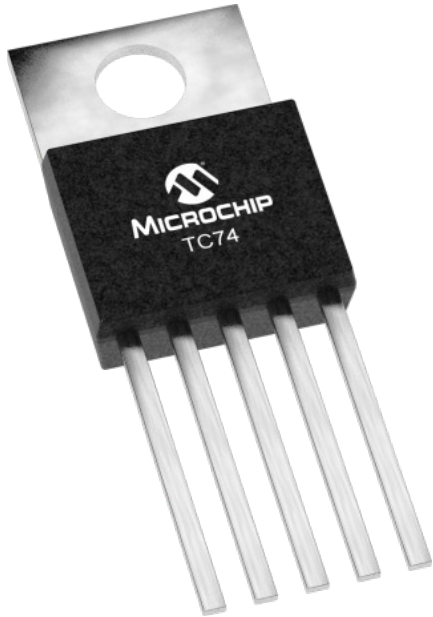


Datasheet: <https://ww1.microchip.com/downloads/en/DeviceDoc/21462D.pdf>

TC74 Temperature Sensor

SMBus/I2C Interface

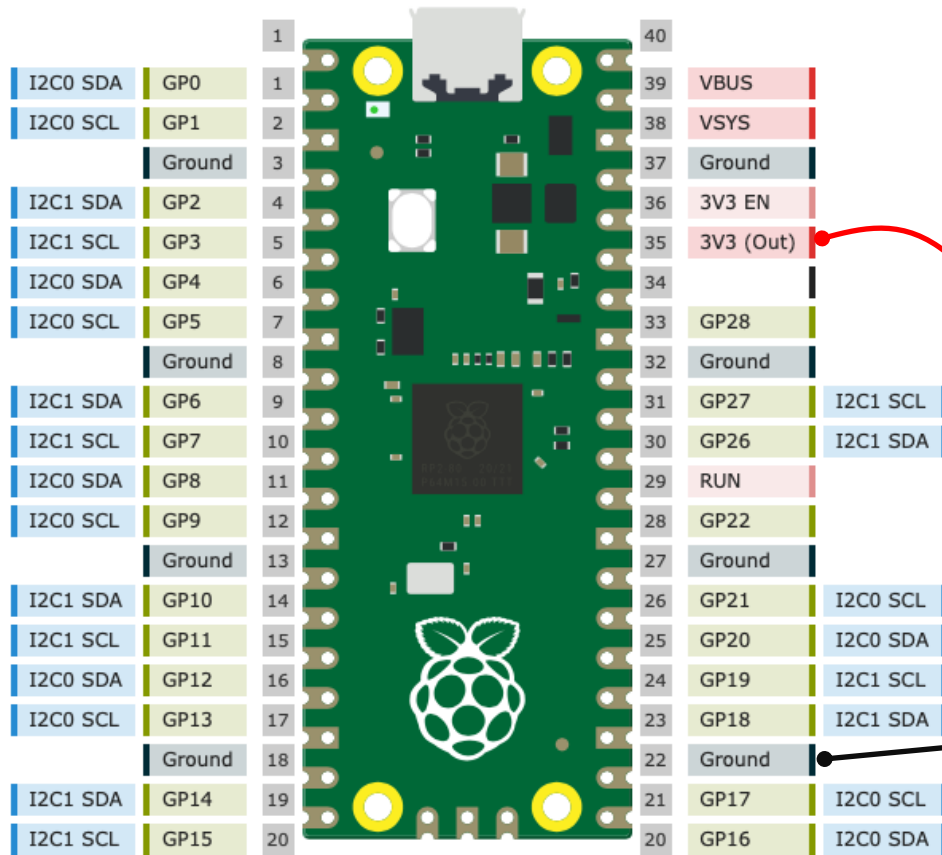
TC74A0-5.0VAT



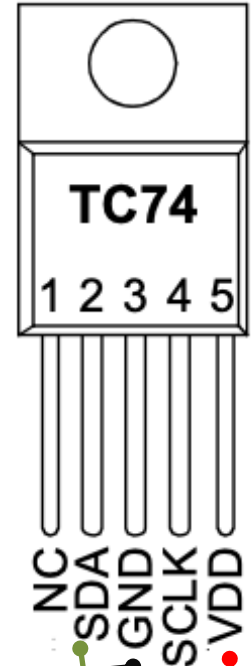
- The TC74 acquires and converts temperature information from its onboard solid-state sensor with a **Resolution of 1°C** (no decimal values, only 24°C, 25 °C, 26 °C, etc.).
- **Accuracy** is about $\pm 2^\circ\text{C}$
- It stores the data in an internal register which is then read through the serial port.
- The system interface is a slave SMBus/I2C port, through which temperature data can be read at any time.
- **Device Address: 0x48**

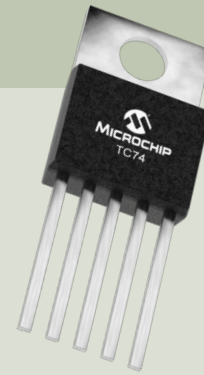
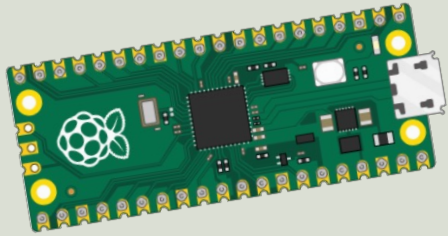
Datasheet: <https://ww1.microchip.com/downloads/en/DeviceDoc/21462D.pdf>

TC74 Wiring Example



SDA - Serial Data – Bidirectional
SCLK/SCL - Serial Clock Input
VDD – Power Supply Input (+3.3v)
GND – Ground
NC - Not in use (Not Connected)





Python Examples using MicroPython and TC74

Python

Basic Example reading a
Temperature Value from the
TC74 Temperature Sensor

```
from machine import Pin, I2C

i2c_interface = 0
sdapin = Pin(16)
sclpin = Pin(17)

i2c = I2C(i2c_interface, scl=sclpin, sda=sdapin,
freq=100000)

tc74address = 0x48
data = i2c.readfrom(tc74address, 1, True)
print(data)

temp = int.from_bytes(data, "big")
print(temp)
```

Python

Basic Example reading a
Temperature Value from the
TC74 Temperature Sensor

```
from machine import Pin, I2C

i2c_interface = 0
sdapin = Pin(16)
sclpin = Pin(17)

i2c = I2C(i2c_interface, scl=sclpin, sda=sdapin, freq=100000)

tc74address = 0x48
data = i2c.readfrom(tc74address, 1, True)
print(data) # Data received is a byte object

# Converting to int. Resolution for TC74 Sensor is 1°C
# byteorder is big where MSB is at start
temp = int.from_bytes(data, "big")
print(temp)
```

Code Explanations

```
..  
data = i2c.readfrom(tc74address, 1, True)
```

We need to convert the data from a byte array to an Integer value. Resolution for TC74 Sensor is 1°C, meaning there is no decimal values only 24°C, 25 °C, 26 °C, etc.

```
temp = int.from_bytes(data, "big")
```

The byteorder argument determines the byte order used to represent the integer. **If byteorder is "big", the most significant byte is at the beginning of the byte array.** If byteorder is "little", the most significant byte is at the end of the byte array

Temperature data is available as an 8-bit digital word.

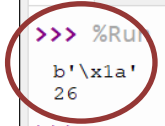


i2c_scan.py x i2c_tc74.py x

```
1 from machine import Pin, I2C
2
3 i2c_interface = 0
4
5 sdapin = Pin(16)
6 sclpin = Pin(17)
7
8 i2c = I2C(i2c_interface, scl=sclpin, sda=sdapin, freq=100000)
9
10 tc74address = 0x48
11
12 data = i2c.readfrom(tc74address, 1, True)
13 print(data) # Data received is a byte object
14
15 # Converting to int. Resolution for TC74 Sensor is +/-1°C
16 # byteorder is big where MSB is at start
17 temp = int.from_bytes(data, "big")
18 print(temp)
```

Shell x

```
>>> %Run -c $EDITOR_CONTENT
b'\x1a'
26
>>>
```



The Temperature in this case is 26°C

Continues
Reading Example

```
from machine import Pin, I2C
from time import sleep

i2c_interface = 0

sdapin = Pin(16)
sclpin = Pin(17)

i2c = I2C(i2c_interface, scl=sclpin, sda=sdapin,
freq=100000)

tc74address = 0x48

while True:
    data = i2c.readfrom(tc74address, 1, True)
    temp = int.from_bytes(data, "big")
    print(temp)
    sleep(5)
```



i2c_scan.py x i2c_tc74.py x i2c_tc74v2.py x

```
1 from machine import Pin, I2C
2 from time import sleep
3
4 i2c_interface = 0
5
6 sdapin = Pin(16)
7 sclpin = Pin(17)
8
9 i2c = I2C(i2c_interface, scl=sclpin, sda=sdapin, freq=100000)
10
11 tc74address = 0x48
12
13 while True:
14     data = i2c.readfrom(tc74address, 1, True)
15     temp = int.from_bytes(data, "big")
16     print(temp)
17     sleep(5)
```

<

Shell x

```
>>> %Run -c $EDITOR_CONTENT
```

```
27
27
27
28
29
27
27
28
27
28
27
28
28
```

Improved Example

Let's make a separate Python Module with a Class and a Function that handles all the logic regarding reading Temperature Data from the TC74 Temperature Sensor

```
from machine import Pin, I2C
```

Sensor.py

```
class TC74:
```

```
    def __init__(self, interface, sda, scl):  
        sdapin = Pin(sda)  
        sclpin = Pin(scl)  
        self.i2c = I2C(interface, scl=sclpin, sda=sdapin, freq=100000)
```

```
def ReadTemperature(self) :
```

```
    tc74address = 0x48  
    data = self.i2c.readfrom(tc74address, 1, True)  
    temp = int.from_bytes(data, "big")  
    return temp
```

Main Program

```
from Sensor import TC74
from time import sleep

# Initialization
i2c_interface = 0
sdapin = 16; sclpin = 17
sensor = TC74(i2c_interface, sdapin, sclpin)

while True:
    temp = sensor.ReadTemperature()
    print(temp, "°C")
    sleep(5)
```




Datalogging and Data Analysis Examples

Datalogging

- We will read data from a Temperature Sensor using
- We will then Log Temperature Data on a File on the Pico Device
- Then we will copy the File to our PC and are then ready to do some Data Analysis
- Finally, we will create a simple Python Script that opens the File and Plot the Data. Here we will use ordinary Python and the matplotlib

```
from machine import Pin, I2C
from time import sleep

#I2C Initialization
tc74address = 0x48
i2c_interface = 0
sdapin = Pin(16); sclpin = Pin(17)
i2c =I2C(i2c_interface, scl=sclpin, sda=sdapin, freq=100000)
```

Open File

```
file = open("tempdata.txt", "w")
```

Write Data to File Function

```
def writefiledata(t, x):
    time = str(t)
    value = str(round(x, 2))
    file.write(time + "\t" + value)
    file.write("\n")
```

```
k = 0
```

```
Ts = 5
```

```
while True:
```

```
    data = i2c.readfrom(tc74address, 1, True)
```

```
    temp = int.from_bytes(data, "big")
```

```
    print(temp)
```

```
    writefiledata(k*Ts, temp)
```

```
    k = k + 1
```

```
    sleep(Ts)
```



Files ×

This computer

C:\Users\hansha

3D Objects

Raspberry Pi Pico

lib

tempdata.txt

i2c_tc74_datalogging.py × [tempdata.txt] * ×

```
1 0 27
2 5 28
3 10 26
4 15 26
5 20 27
6 25 28
```

Shell ×

```
>>> %Run -c $EDITOR_CONTENT
```

```
27
28
26
26
27
28
```

```
Traceback (most recent call last):
  File "<stdin>", line 29, in <module>
KeyboardInterrupt:
```

```
MicroPython v1.19.1 on 2022-06-18; Raspberry Pi Pico with RP2040
```

```
Type "help()" for more information.
```

```
>>>
```

Data Analysis

- The File is now copied to our PC and we are then ready to do some Data Analysis
- We will create a simple Python Script that opens the File and Plot the Data. Here we will use ordinary Python and the matplotlib

```
import matplotlib.pyplot as plt

# Open File
f = open("tempdata.txt", "r")

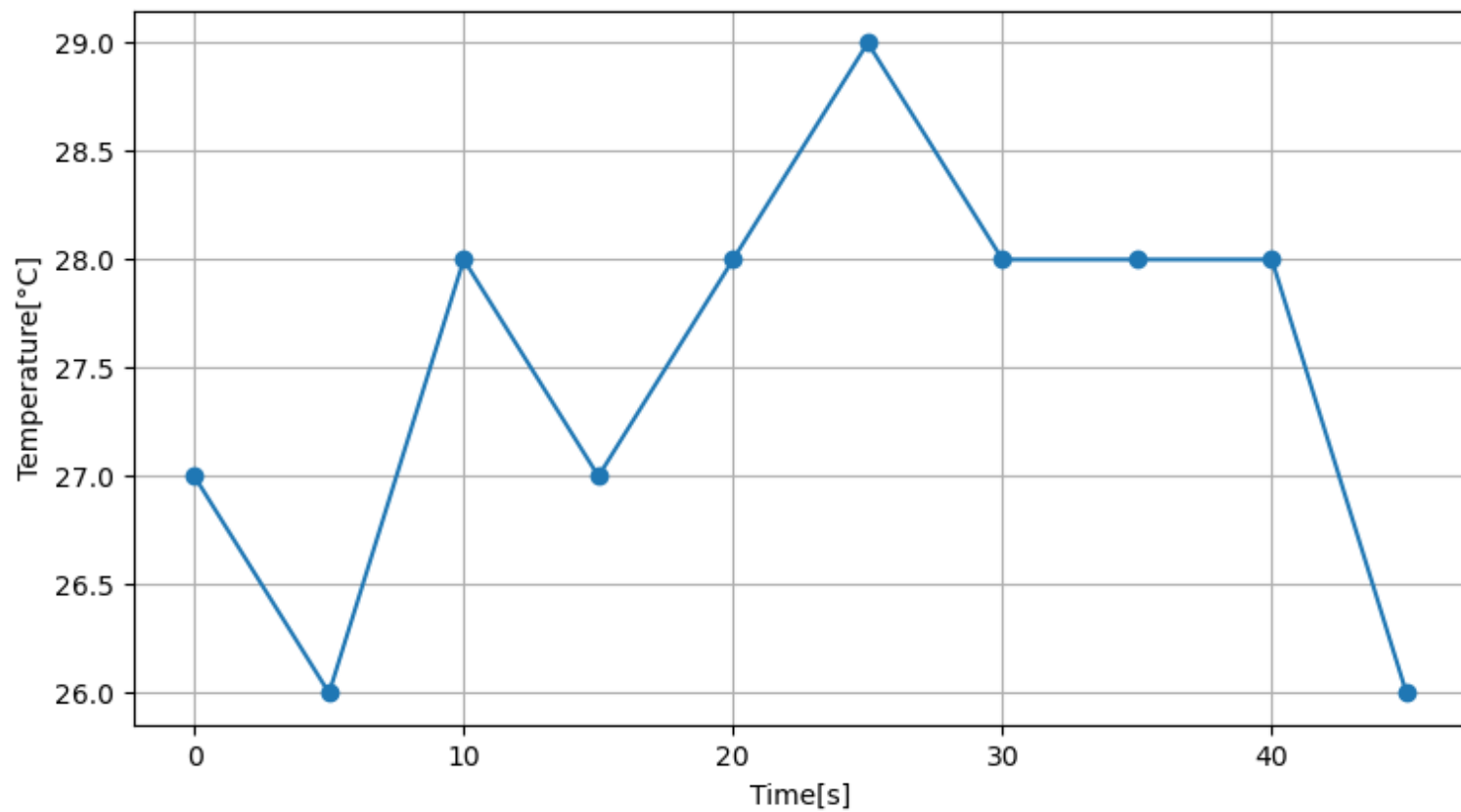
# Transform File Data into x Array and y Array that can be used for plotting
x = []
y = []
k = 0
for record in f:
    record = record.replace("\n", "")
    record = record.split("\t")
    x.append(int(record[0]))
    y.append(int(record[1]))
    k=k+1

f.close()

plt.plot(x,y, '-o')
plt.title('Temperature Data from TC74 Sensor')
plt.xlabel('Time[s]')
plt.ylabel('Temperature[°C]')
plt.grid()
plt.show()
```



Temperature Data from TC74 Sensor



Raspberry Pi Pico Resources

- Raspberry Pi Pico:

<https://www.raspberrypi.com/products/raspberry-pi-pico/>

- Raspberry Pi Foundation:

[https://projects.raspberrypi.org/en/projects?hardware\[\]=pico](https://projects.raspberrypi.org/en/projects?hardware[]=pico)

- Getting Started with Pico:

<https://projects.raspberrypi.org/en/projects/getting-started-with-the-pico>

- MicroPython:

<https://docs.micropython.org/en/latest/index.html>

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